FSR Series



Force Sensing Resistor

The Ohmite FSR series exhibits the unique characteristic of dynamic resistance related to the amount of applied force. In general, the more force applied to the surface of the sensor, the lower the resistance. The resistance change is inversely proportional to the applied force. Typical force-sensing resistors are characterized for Human-Machine Interface (HMI) or Machine-Machine Interface (HMI) applications with a sensing range from circa 20g to 5Kg. Specific device characteristics will depend on the size, shape and materials used in construction. Force-sensing resistors are intended for applications where a delta in applied force is to be detected. They are not intended for high accuracy or specific weight measurement applications.

SERIES SPECIFICATIONS

OHMITE, 47- 17

| Series | Active area | Thickness (inc. 0.05mm adhesive) | Sensor overall width | Sensor overall length | Tail length | Tail width |
|--------|------------------|-------------------------------------|-------------------------|--------------------------|-------------|------------|
| FSR01 | 39.70 x 39.70mm | 0.375mm | 43.69 x 43.69mm | 83.09mm | 39.40mm | 7.62mm |
| FSR02 | 604.60 x 10.20mm | 0.375mm | 15.20mm | 622.30mm | 12.70mm | 7.60mm |
| FSR03 | ø25.42mm | 0.425mm | 30.50mm | 69.00mm | 38.00mm | 7.62mm |
| FSR04 | ø5.60mm | 0.325mm | 7.62mm | 15.80mm | 9.00mm | 6.35mm |
| FSR05 | ø5.60mm | 0.325mm | 7.62mm | 38.10mm | 30.00mm | 6.35mm |
| FSR06 | ø14.70mm | 0.375mm | 18.00mm | 25.00mm | 9.00mm | 7.62mm |
| FSR07 | ø14.70mm | 0.375mm | 18.00mm | 56.34mm | 38.00mm | 7.62mm |

CHARACTERISTICS

| Characteristic | Description | FSR01 | FSR02 | FSR03 | FSR04 | FSR05 | FSR06 | FSR07 |
|----------------------------|--|-------------------|-------|-------|-------|-------|-------|-------|
| Actuation force | tion force Force to reach $10M\Omega$, Average of 100 samples | | < 20g | < 10g | <20g | <30g | <15g | <15g |
| Force range | linear region of log/log, Higher forces can be achieved with custom sensor and actuation methods | All: Up to 5kg | | | | | | |
| Long term drift | Long term drift 1kg for 48hrs, Per log time | | <1% | <1% | < 2% | < 2% | 1% | 1% |
| Single part repeatability | 100 actuations of 1kg, 1 standard deviation/mean | All: 2% | | | | | | |
| Part to part repeatability | 100 sensors same batch, 1 standard deviation/mean | All: ±4% | | | | | | |
| Low temp. storage | -20°C for 250hrs, Avg. change in res. of 5 sensors | 8% | 7% | 7% | 8% | 8% | 7% | 7% |
| High temp. storage | +85°C for 250hrs, Avg. change in res. of 5 sensors | 4% | 3% | 3% | 4% | 4% | 3% | 3% |
| High humidity storage | +85°C/85%RH for 250hrs, Avg. change in res. of 5 sensors | 8% | 12% | 8% | 8% | 8% | 12% | 12% |
| Lifecycle durability | (10M) 1kg force at 3Hz, Avg. change in res. of 4 sensors | 17% | 12% | 3% | 7% | 7% | 3% | 3% |
| Hysteresis | 100 actuations of 1kg, Avg. change in res. of 100 samples | All: 5% | | | | | | |
| Operational temp. range | 100 cycles at 0.5kg | All: -20 to +85°C | | | | | | |

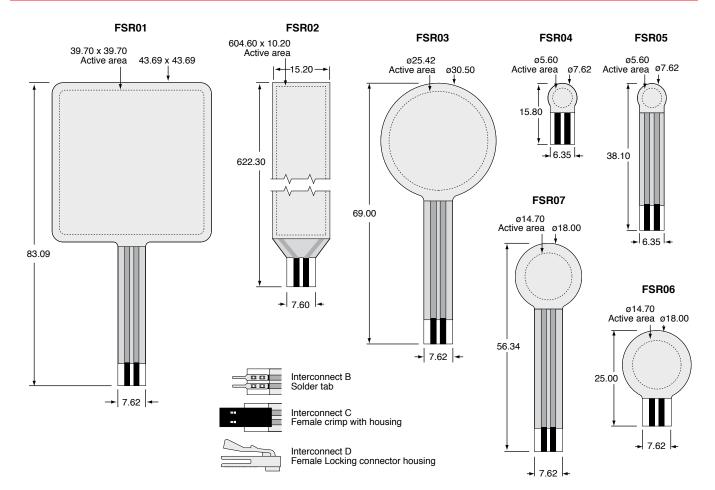
Note: All values typical, and quoted at 10N applied force unless otherwise stated. Force dependant on actuation interface, mechanics, touch location, and measurement electronics.

| | FSR01-03 | FSR04 | FSR05 | FSR06 | FSR07 |
|---------------|----------|--------|--------|--------|--------|
| Mode | Shunt | Shunt | Shunt | Shunt | Shunt |
| Trace pitch | 0.25mm | 0.25mm | 0.25mm | 0.25mm | 0.25mm |
| Spacer height | 0.125mm | 0.05mm | 0.05mm | 0.05mm | 0.05mm |
| Trace width | 0.25mm | 0.25mm | 0.25mm | 0.25mm | 0.25mm |

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DIMENSIONS

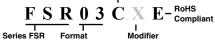


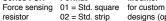
ORDERING INFORMATION

Terminal type

- A = Bare tail B = Solder tab

- E, F, G... Assigned sequentially for custom designs





- 03 = Round 30.5mm
- 04 = Round 7.62mm 15.8mm length05 = Round 7.62mm 38.1mm length
- 06 = Round 18.0mm 25.0mm length
- 07 = Round 18.0mm 56.34mm length 08, 09, 10... assigned sequentially for new designs

11

designs (optional)

